

APPROXIMATION ALGORITHMS

LINEAR PROGRAMMING

& DETERMINISTIC ROUNDING

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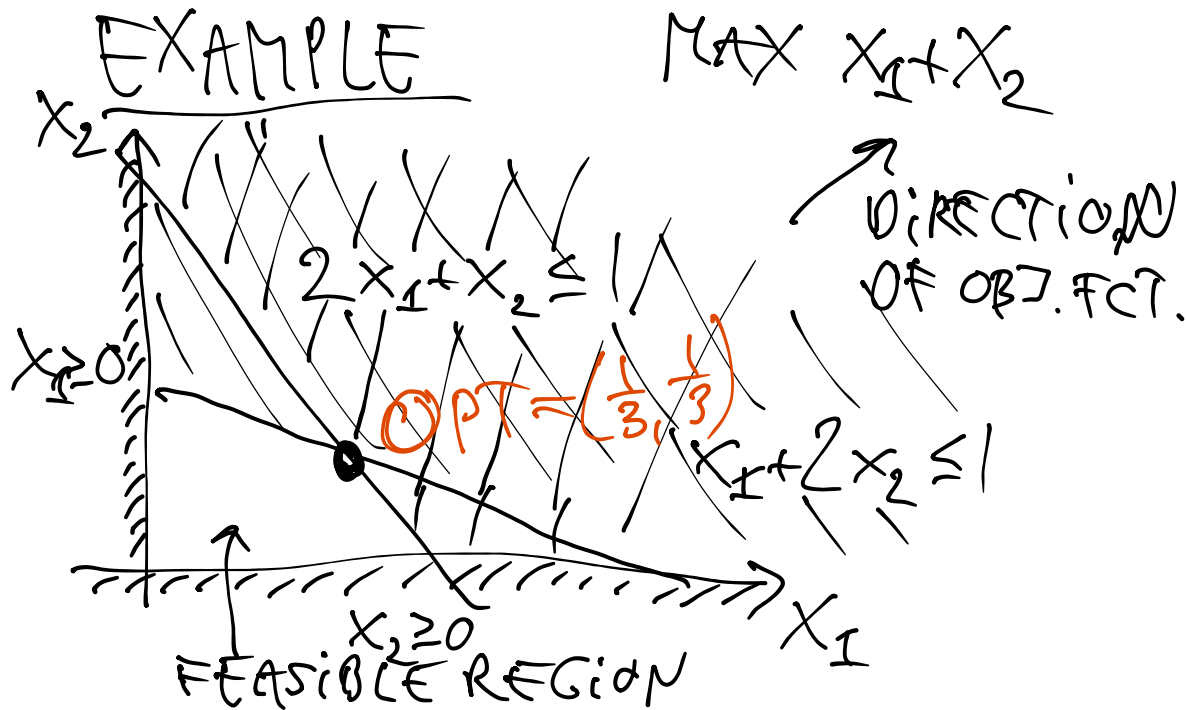


TODAY

- QUICK OVERVIEW/REMINDER FOR LINEAR PROGR.
- CASE STUDY: VERTEX COVER, SET COVER
- WORKING WITH LPS IN PYTHON
- CASE STUDY: PRIZE-COLLECTING
STEINER TREE PROBLEM

LINEAR PROGRAM (CANONICAL FORM)

- DECISION VARIABLES $x_1, \dots, x_n \in \mathbb{R}$, $x_i \geq 0 \forall i$
- LINEAR CONSTRAINTS OF THE FORM $\sum_{i=1}^n a_i x_i \leq b_j$
- A LINEAR OBJECTIVE FUNCTION $\max \sum_{i=1}^n c_i x_i$



IN HIGHER DIMENSIONS:

- FEASIBLE REGION IS INTERSECT. OF HALFSPACES
- OPTIMAL SOLUTION CAN BE:
 - UNIQUE IN A "CORNER"
 - ALONG A "FACE" OF POLYTOPE
 - NOT EXIST: UNBOUNDED OR INFEASIBLE

PAUSE TO THINK

HOW CAN WE TRANSLATE A GENERAL LINEAR PROGRAM WITH $\geq, =$ CONSTRAINTS; MAYBE MINIMIZING INSTEAD OF MAXIMIZING; MAYBE ALLOWING VALUES OF x_i LESS THAN 0; INTO AN EQUIVALENT LP IN CANONICAL FORM?

E.G.: MINIMIZE $x_1 + x_2 + x_3$

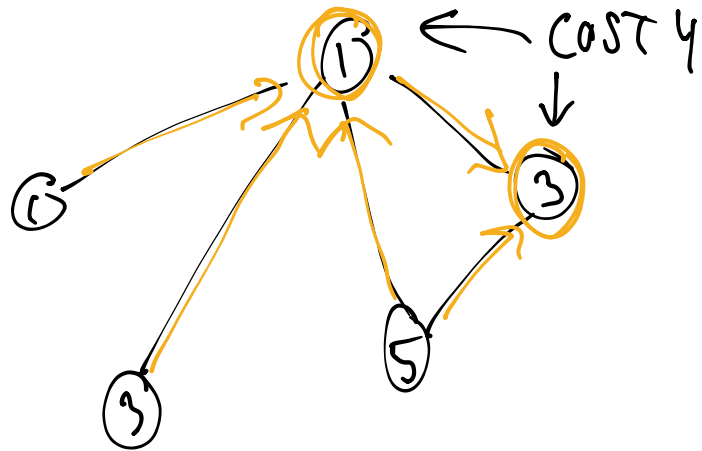
$$\text{UNDER } x_1 + 2x_2 = 1$$

$$x_1 - x_3 \geq 0$$

$$2x_1 + x_2 + x_3 \leq 5$$

$$x_1, x_2, x_3 \in \mathbb{R}$$

MINIMUM WEIGHTED VERTEX COVER



"COVERS" ALL EDGES

INPUT: GRAPH $G = (V, E)$

WEIGHT FUNCTION $w: V \rightarrow \mathbb{R}$

OBJECTIVE: CHOOSE $S \subseteq V$ SUCH
THAT FOR $\{u, v\} \in E$: $u \in S$ OR $v \in S$,
MINIMIZING $\sum_{v \in S} w(v)$

EQUIVALENT

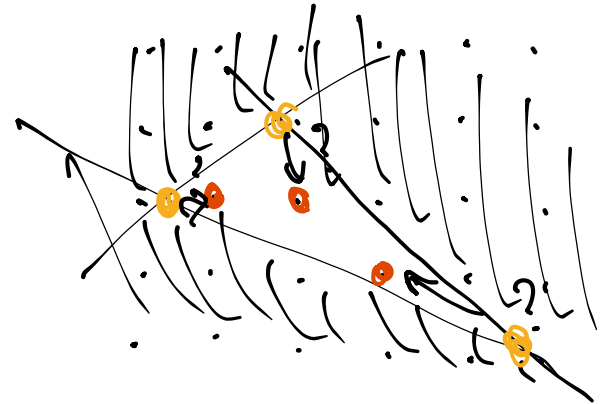
FORMULATION AS INTEGER LINEAR PROGRAM:

MINIMIZE $\sum_{v \in V} w(v) \cdot x_v$

SUBJECT TO $x_u + x_v \geq 1$ FOR ALL $\{u, v\} \in E$

$x_v \in \{0, 1\}$ INDICATES WHETHER $v \in S$

INTEGER SOLUTIONS
SATISFYING LINEAR CONSTR



ROUNDING AN LP SOLUTION

$$\text{MINIMIZE } \sum_{v \in V} w(v) \cdot x_v$$

$$\text{SUBJECT TO } x_u + x_v \geq 1 \text{ FOR ALL } \{u, v\} \in E$$

~~$x_v \in \{0, 1\}$~~ INDICATES WHETHER $v \in S$

$$x_v \geq 0 \quad x_v \leq 1$$

OPTIMAL SOLUTION
TO "LP RELAXATION"

$$x^* \in [0, 1]^n$$



$$\hat{x} \in \{0, 1\}^n$$

$$\hat{x}_v = \begin{cases} 1 & \text{if } x_v^* \geq 1/2 \\ 0 & \text{OTHERWISE} \end{cases}$$

ANALYSIS

$$\sum_{v \in V} w(v) \cdot \hat{x}_v \leq \sum_{v \in V} w(v) \cdot 2x_v^*$$

$$= 2 \sum_{v \in V} w(v) x_v^*$$

$$\leq 2 \cdot \text{OPT}$$

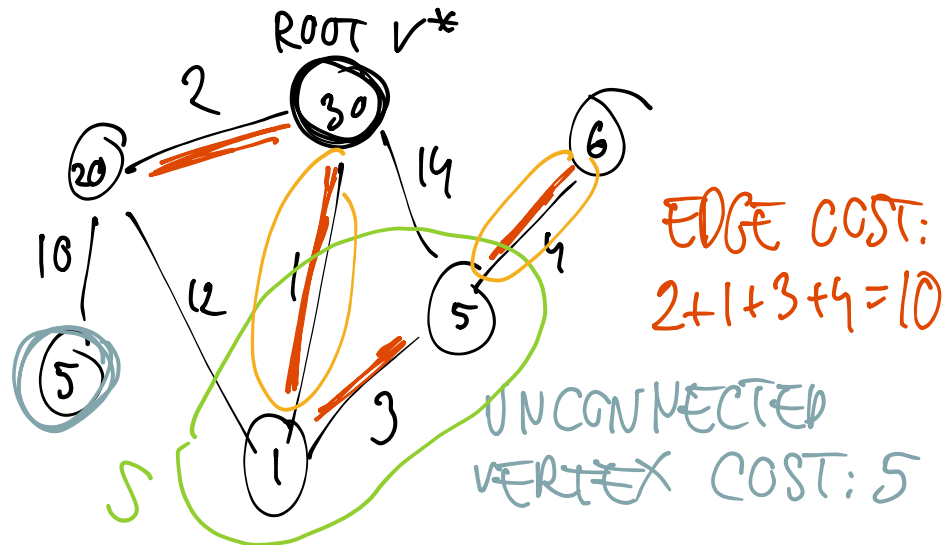
← SATISFIES ALL
LP CONSTRAINTS
AND INTEGRALITY

CAN BE GENERALIZED

TO SET COVER:

CHOOSE COLLECTION
OF SETS WHOSE
UNION COVERS ALL
ELEMENTS IN GROUND SET

PRIZE-COLLECTING STEINER TREE PROBLEM



INPUT. $G = (V, E)$

FOR EACH $e \in E$: COST c_e

FOR EACH $v \in V$: COST π_v

OUTPUT: $x_e \in \{0, 1\}$ IS e IN T ?

$y_v \in \{0, 1\}$ IS v IN T ?

GOAL: MINIMIZE TOTAL COST FOR TREE T WITH ROOT v^*

OBJECTIVE: MINIMIZE $\sum_{e \in E} c_e x_e + \sum_{v \in V} \pi_v (1 - y_v)$

CONSTRAINTS TO ENSURE x, y ARE VALID

CONSIDER $\emptyset \subsetneq S \subsetneq V$ AND $v \in S, v^* \notin S$

IF $y_v = 1$ THEN THERE IS SOME PATH FROM v^* TO v

$\Rightarrow x_e = 1$ FOR SOME EDGE CROSSING CUT $(v \in S, S)$ ←

SET OF SUCH EDGES $\delta(S)$

LINEAR CONSTRAINT: (*) $\sum_{e \in \delta(S)} x_e \geq y_v, \forall S \subsetneq V \setminus \{v^*\}$

PAUSE AND THINK:
IF x AND y ARE NOT VALID THEN A CONSTRAINT OF THE FORM (*) IS VIOLATED.

LP RELAXATION

$$\text{MINIMIZE } \sum_{e \in E} c_e x_e + \sum_{v \in V} \pi(v) (1 - y_v)$$

$$\text{SUBJECT TO } \sum_{e \in \delta(S)} x_e \geq y_v, \quad \forall S \subseteq V \setminus \{v^*\}, S \neq \emptyset, v \in S$$
$$y_{v^*} = 1, \quad x_e \in [0, 1], \quad y_v \in [0, 1]$$

ISSUE!
EXPONENTIAL
NUMBER OF CONSTRAINTS

DECISIONS

- CHOOSE VERTICES TO CONNECT \leftarrow TODAY
- CHOOSE EDGES IN TREE \leftarrow STEINER TREE, LATER

MAX-FLOW MIN CUT:
CAN DETERMINE
IN POLYNOMIAL
TIME IF A
CONSTRAINT IS VIOLATED
 \rightarrow CAN FIND S

ROUNDING:

$$\hat{y}_v = \begin{cases} 1 & \text{IF } y_v^* \geq 2/3 \\ 0 & \text{OTHERWISE} \end{cases}$$

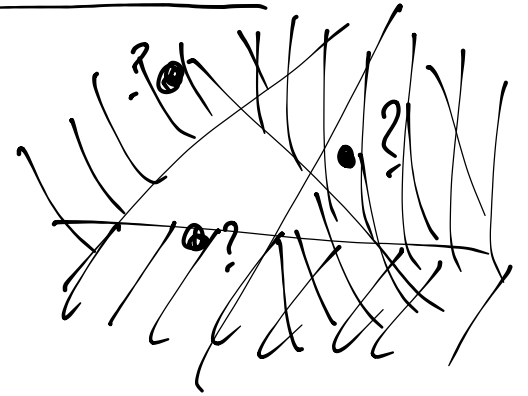
\leftarrow OPT. LP SOLUTION

SUGGESTS A
3-APPROXIMATION

$$\text{OBSERVE THAT } \sum_{v \in V} \pi(v) (1 - \hat{y}_v) \leq 3 \sum_{v \in V} \pi(v) (1 - y_v^*)$$

SOLVING LPS WITH A SEPARATION ORACLE

- START WITH NO CONSTRAINTS
- FIND POTENTIAL SOLUTION, ASK ORACLE IF IT VIOLATES A CONSTRAINT
- FIND A POTENTIAL SOLUTION INCLUDING THE NEW CONSTRAINT
- REPEAT



ELLIPSOID METHOD

LPS WITH A SEPARATION ORACLE RUNNING IN POLYNOMIAL TIME CAN BE SOLVED IN POLYNOMIAL TIME.

↑
NOT PRACTICAL.
SOMETIMES USED IN PRACTICE:
ADD CONSTRAINTS "LAZILY"